

Improving Accuracy of RTT Estimation of the ICMPTrain Algorithm

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Problem Statement

- Accurate estimation of RTTs in internet-wide scans would help improve accuracy of geolocation.
- ICMPTrain algorithm probes all IPv4 addresses in the Internet to establish which ones are live
- Currently ICMPTrain probes each address once. If we probe more, we can be more accurate.
- Our goal: design adaptive probing to
 - a) Minimize error
 - b) While minimizing number of probe
- Approach:
 - Modify ICMPTrain to probe adaptively.
 - Measure how many probes per address are enough for correct estimate, and what is the error.

ICMPTrain

```
#fsdb -F t reply_type time_s rtt_us ttl probe_addr reply_addr
# TXT: **magic
# TXT: **checkpoint:32,0/0,0,0,0
# TXT: @(#) $Id: 540fd15362714e7b26bd91e401545eab8aaddfb7 $
# TXT:
0x0000 1531337591 258 64 128.9.160.77 128.9.160.77
0x0000 1531337591 251 64 128.9.160.93 128.9.160.93
0x0000 1531337592 262 64 128.9.160.129 128.9.160.129
0x0000 1531337592 519 64 128.9.160.61 128.9.160.61
0x0000 1531337593 270 64 128.9.160.101 128.9.160.101
0x0000 1531337593 212 64 128.9.160.197 128.9.160.197
0x0000 1531337594 276 64 128.9.160.89 128.9.160.89
0x0000 1531337594 320 64 128.9.160.105 128.9.160.105
0x0000 1531337594 553 64 128.9.160.109 128.9.160.109
0x0301 1531337591 3051705 64 128.9.160.153 128.9.160.170
0x0301 1531337591 3083723 64 128.9.160.249 128.9.160.170
0x0301 1531337591 3051663 64 128.9.160.241 128.9.160.170
0x0301 1531337591 3091657 64 128.9.160.1 128.9.160.170
0x0000 1531337595 328 255 128.9.160.161 128.9.160.161
0x0301 1531337592 3108669 64 128.9.160.73 128.9.160.170
0x0301 1531337592 3066603 64 128.9.160.201 128.9.160.170
0x0301 1531337592 3082645 64 128.9.160.33 128.9.160.170
0x0000 1531337595 385 32 128.9.160.25 128.9.160.25
```

ICMPTrain sending multiple pings.

- Sends multiple pings to multiple ip addresses.
- I used ICMPTrain to use ping.
- I ping 20 times each ip to collect statistics.
- I get IP address from random ip from a hitlist.

Challenges Measuring RTT

Problem: Multiple factors affect

- Bandwidth.
 - Queue Delays.
 - Physical Distance (Propagation Delay).
- Solution: Having multiple probes from each IP can be more accurate on finding true RTT.
- $$E_i = R + Q_i$$
- Minimum RTT filters out queuing delay component of noise.

Conclusions

- We learn that probing 10 times gives you good accurate measurements.
- Simulate this results on an adaptive algorithm that we created.
- We believe that adaptive will be more efficient and just as accurate.
- Plans to run simulation to evaluate accuracy of adaptive algorithm.

Experiments:

RTT Accuracy Vs. Cost

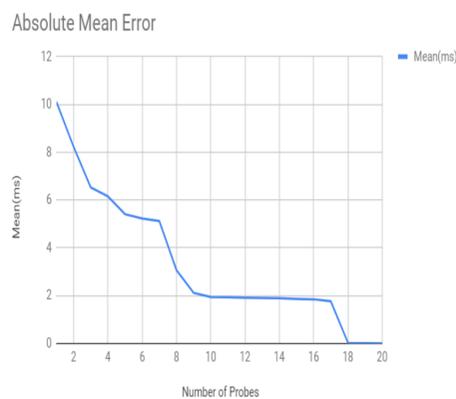
Hypothesis: Do showing more Probe helps?

Methodology:

EstimateRTT(target_ip, N_probes) =
min(observation(1..N_probes, target_ip))

- 1) Selected random 1000 targets from hitlist
- 2) Ping each 20 times with a wait time of 5 seconds.
- 3) Discarded targets with incomplete observation, fewer than 20 results.
- 4) Calculated the ground true value from 20 probes.
- 5) GroundTruthRTT(IP) = EstimateRTT(rtt, target_ip, 20)
- 6) Evaluate how much more probes help: EstimateRTT(target_ip, i) for I in 1 to 20 probes

- This is the error, compared to our ground truth for each IP if we probe it 'j' times:
- AbsoluteError(IP, j) = estimate(rtt, target_ip, j) - groundThurthRTTMin(rtt (IP, k)) - GroundTruthRTT(IP)
k = 1...j



Expected Results: Maybe using few observation is as good as GroundTruthRTT.

Discussion:

Giving from the graph, the hypothesis is true. Using 9 observation is as good as GroundTruthRTT.

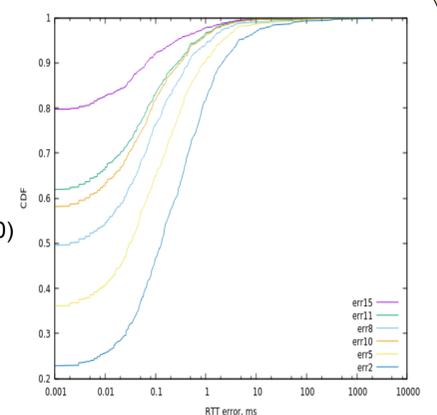
Distribution of RTT Accuracy

Hypothesis: How accurate is more Probe?

Methodology:

EstimateRTT(target_ip, N_probes) =
min(observation(1..N_probes, target_ip))
GroundTruthRTT(IP) = estimate(rtt, target_ip, 20)
ErrN(N_probes, target_ip) = EstimateRTT() -
GroundTruthRTT(target_ip)
CounterTotalAmountError = size(ErrN)
CDF(N_probes) = (count (sort(ErrN(N_probes,
target_ip)) / CounterTotalAmountErrorRTT)

- 1) Selected random 1000 targets around the internet.
- 2) Ping each 20 times with a wait time of 5 seconds.
- 3) Discarded targets with incomplete observation, fewer than 20 results.
- 4) Calculated GroundTruthRTT value from 20 probes.
- 5) Calculated the ErrN from first probe...last.
- 6) Sort the ErrN from minimum to maximum.
- 6) Finishing by calculating CDF which have a counter of the ErrN of each probe(1..20) errors and divided by a counter of total amount of error.



Expected Results: Maybe, for finding the best possibility of finding error is the 10 distribution of estimate.

Discussion:

The hypothesis is true. The distribution of estimate using 10 input, observation has a much higher fraction of finding the X percent of population.

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